



Stratospheric Conditions: A Near-Space Balloon Project

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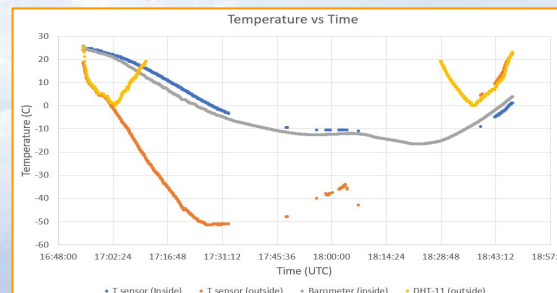
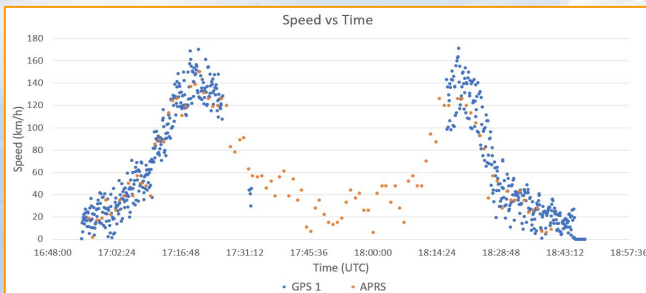
This work was supported in part by the National Aeronautics and Space Administration under Grant No. 80NSSC20M0043.



Filling balloon with Helium



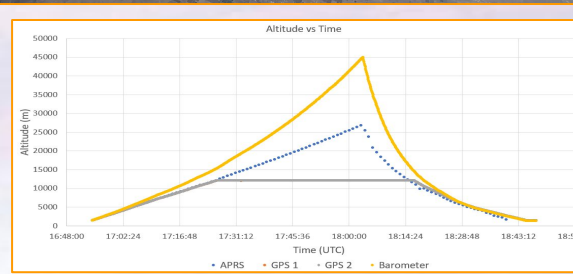
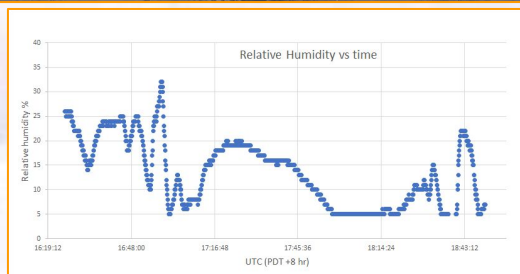
Group photo just before launching



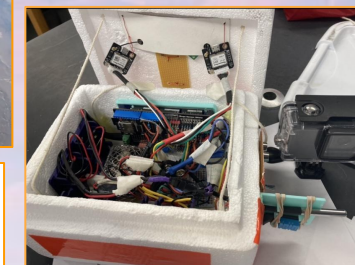
Walker Lake from 88,000 ft, GoPro image



Lake Tahoe from 88,000 ft, GoPro image



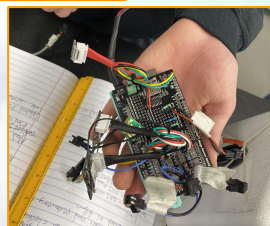
Soldering sensors to Arduino board



The Payload



Black/white dots = APRS actual data. Yellow (balloon burst) and red (landing) dots = simulation data. Total flight = 104km.



The Arduino board (brain of the payload). All sensors connect to this.

In response to past issues with the GPS system, we included a second GPS chip for redundancy. Despite this, both GPS chips failed at ~12,000m due to a firmware issue (see above graph). The temperature sensors also stopped working due to an unknown issue, causing the heater to not function correctly.

Internal Systems:

- GPS (x2)
- Heater
- Temperature Sensor
- Arduino Board
- Lithium Ion Batteries (x5)

External Systems:

- GoPro
- Temperature Sensor
- Barometer
- Relative Humidity Sensor
- APRS (Ham Radio tracker)